

# View-based Propagator Derivation

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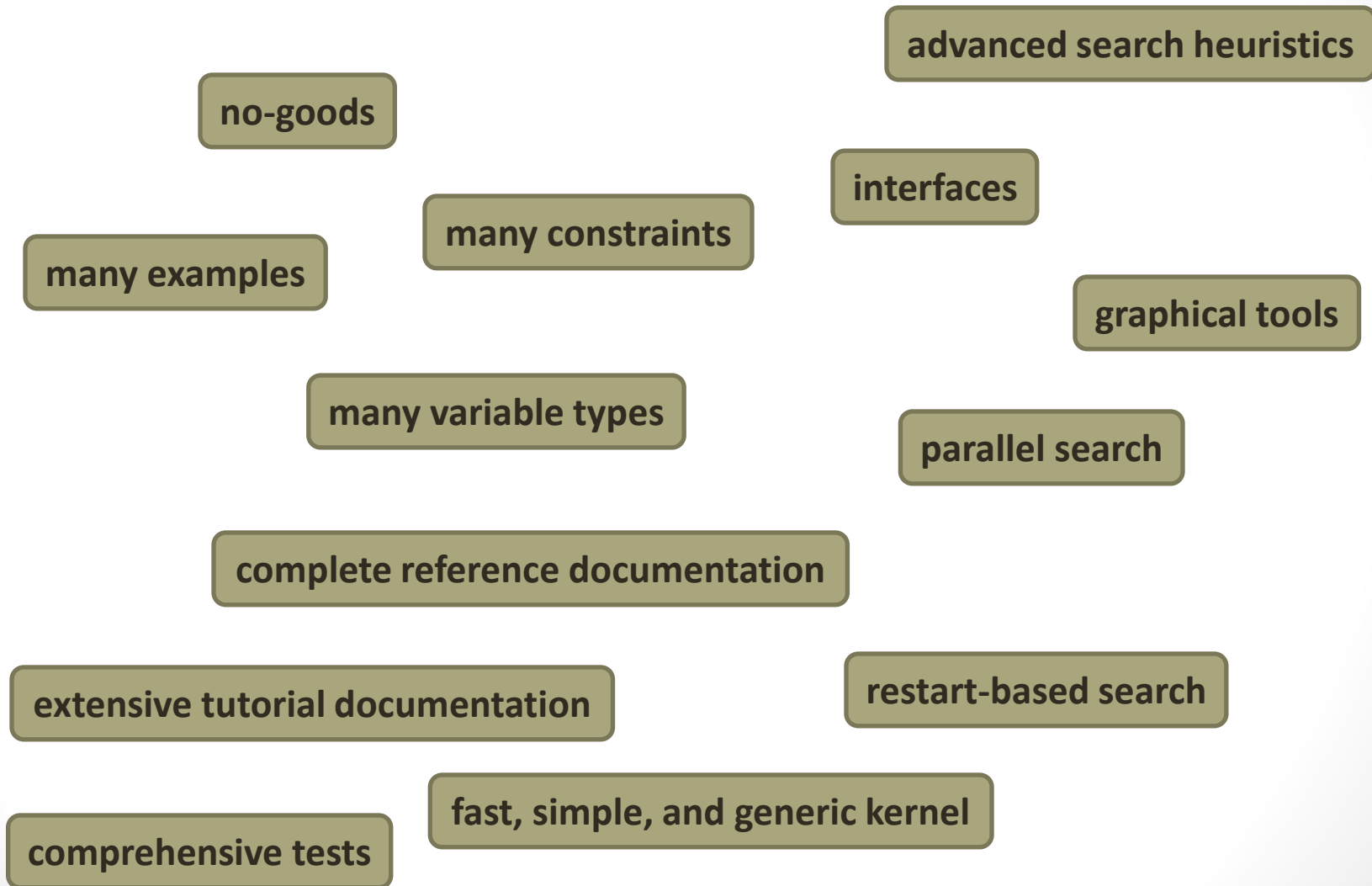
joint work with:

**Guido Tack**

NICTA & Monash University, Australia

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# Building a CP System

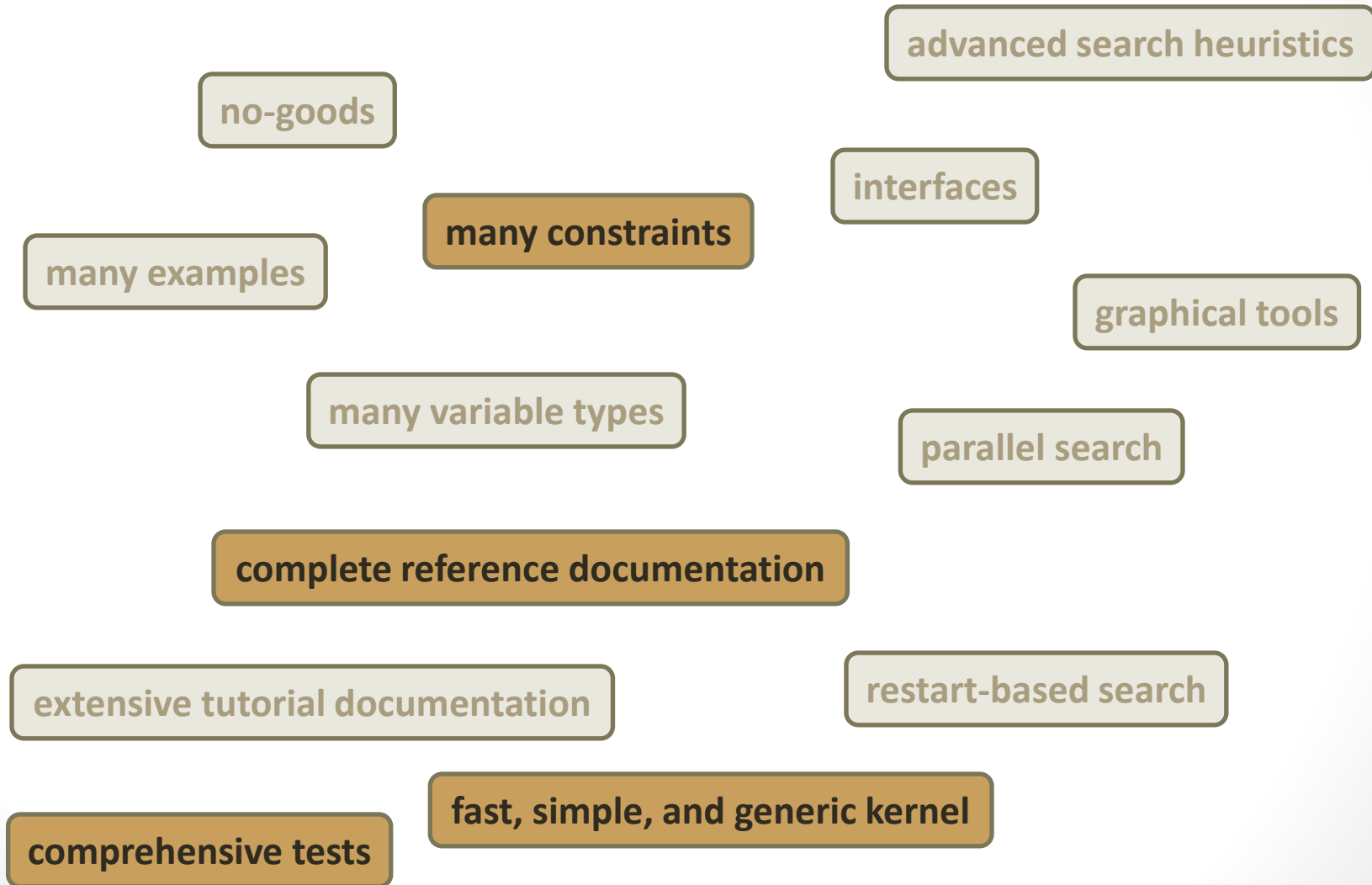


# How Many Tries Do You Have?

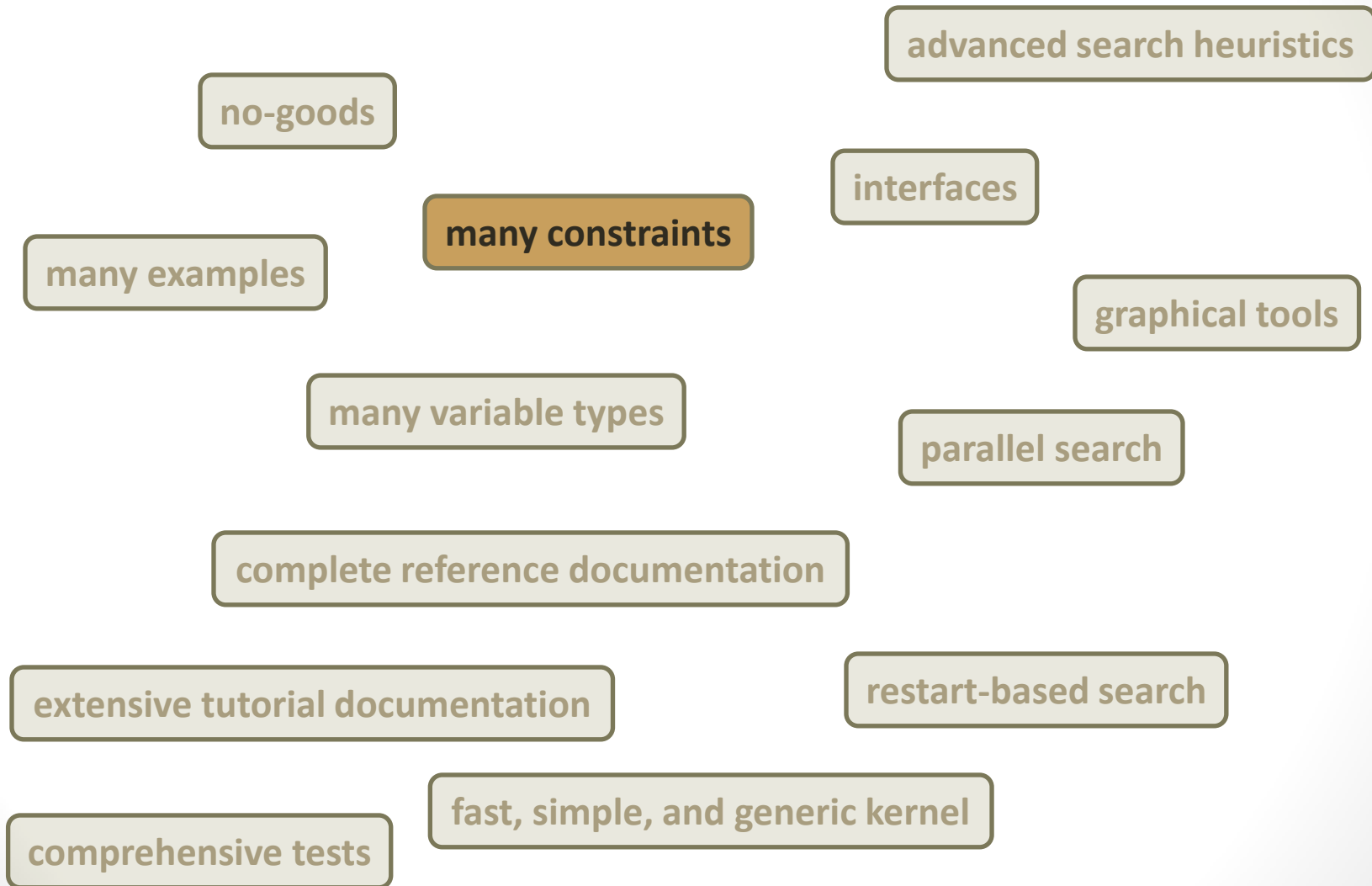
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- Have to get it right first time potential user downloads
- Decisions for Gecode 1.0.0:
  - sufficiently **many** constraints
  - sufficiently **high** speed
  - sufficiently **few** bugs
  - release as open source **on time**
  - accessible **to experts**

# Gecode 1.0.0



# This Talk



# Which Constraints?

- A propagator for

$$\min(x_1, \dots, x_n) = y$$

as well as

$$\max(x_1, \dots, x_n) = y ?$$

- A propagator for

$$a_1 \times x_1 + \dots + a_n \times x_n = c$$

( $a_i, c$  integers)

as well as

$$x_1 + \dots + x_n = c ?$$

- A propagator for

$$(x_1 + \dots + x_n = c) \leftrightarrow y$$

( $c$  integer)

as well as

$$(x_1 + \dots + x_n \neq c) \leftrightarrow y ?$$

( $c$  integer)

# Decompose Constraints? No!

- Decompose

$$\max(x_1, \dots, x_n) = y$$

into

$$\min(z_1, \dots, z_n) = u \wedge x_1 = -z_1 \wedge \dots \wedge x_n = -z_n \wedge y = -u$$

- **no way: clashes with speed and fast kernel**

- Decompose

$$a_1 \times x_1 + \dots + a_n \times x_n = c \quad (a_i, c \text{ integers})$$

into

$$y_1 + \dots + y_n = c \wedge y_1 = a \times x_1 \wedge \dots \wedge y_n = a \times x_n$$

- **absolutely no way: yields less propagation**

# Implement Propagators? No!

- Tremendous effort to implement propagator variants
  - Gecode: just three people
  - research interest is **not** implementing constraints
- Additional effort for
  - documentation
  - testing
  - maintenance
- Effort potentially prohibitive

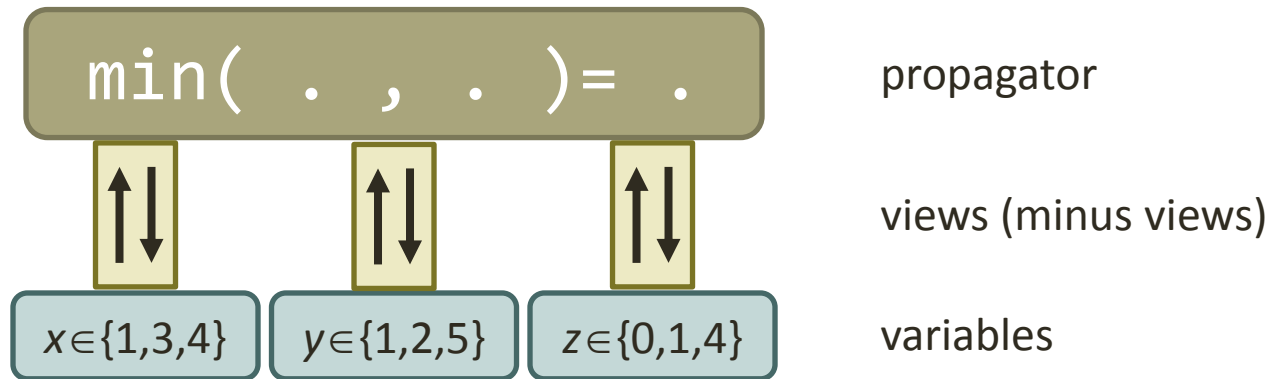


# Derive Propagators? Yes!

- **Derive** propagators using **variable views**
- Using **systematic derivation** techniques
- View idea
  - folded into propagator
  - bi-directional mapping of values
- Derived propagators are **perfect**
  - correctness
  - propagation strength: bounds and domain consistency
  - implementation aspects: fixpoints and subsumption
  - little overhead (often none)

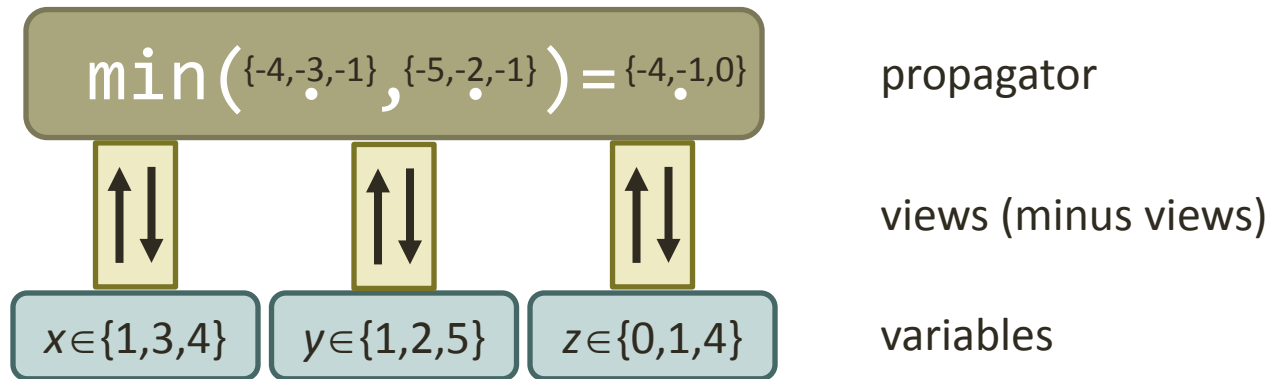
# HOW AND WHY VIEWS WORK

# Propagating max with Views



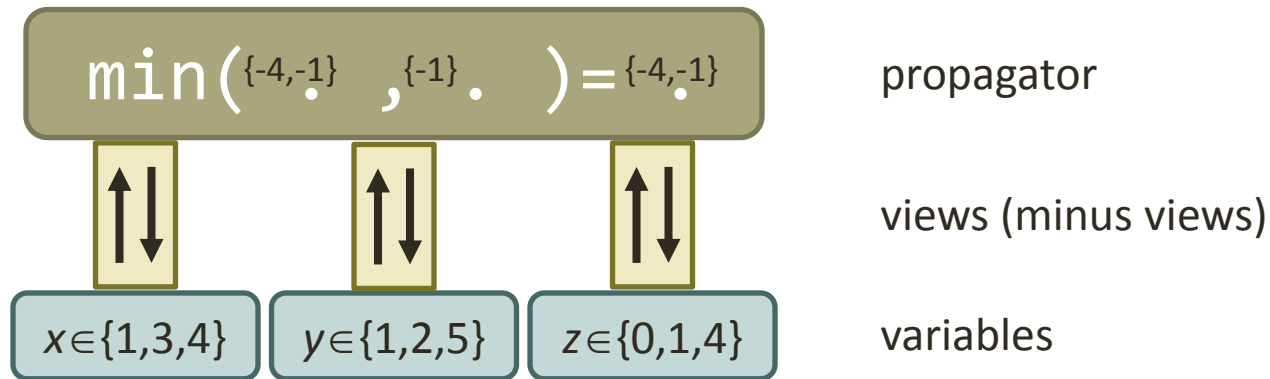
- Propagator

# Propagating max with Views



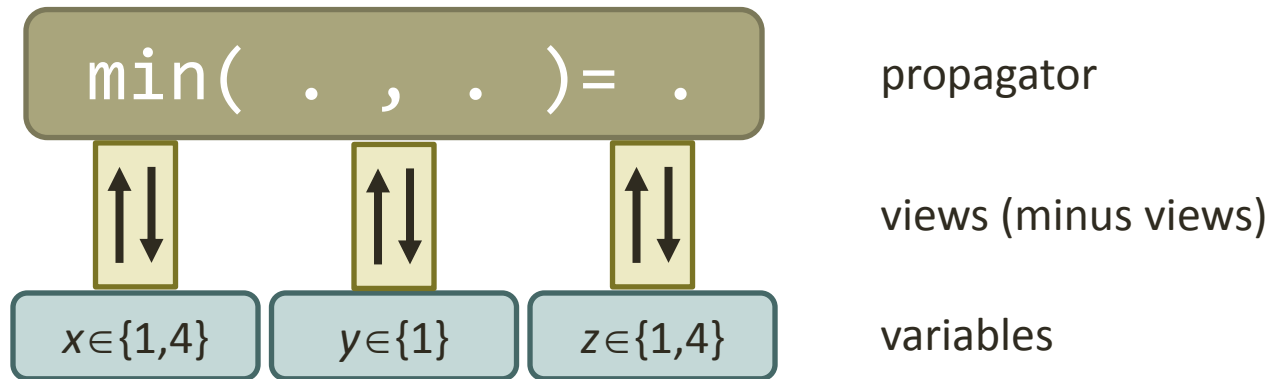
- Propagator
  1. reads values through **views**

# Propagating max with Views



- Propagator
  1. reads values through **views**
  2. performs propagation wrt values read

# Propagating max with Views



- Propagator
  1. reads values through **views**
  2. performs propagation wrt values read
  3. writes values through **inverse** of **views**

# Model for Views

- **Variable view** for a variable  $x$

$$\varphi_x : V \rightarrow V'$$

**injective** function from values  $V$  to values  $V'$

- different value sets matter
- **View**  $\varphi$  is a family of variable views  $\varphi_x$  for all variables  $x$
- Possible to define **inverse view**  $\varphi^-$
- Propagator **derived** from propagator  $p$ 
$$\varphi^- \bullet p \bullet \varphi$$
- Also define **derived constraint**, ...

# Facts

- Derived propagator
  - is in fact a propagator (preserves contraction and monotonicity)
  - implements the “right” constraint (constraint composed with views)
  - preserves fixpoints and subsumption
  - inherits domain-consistency
- With additional (natural) requirements inherits
  - bounds(**Z**)-consistency
  - bounds(**D**)-consistency
  - depends on whether hull operator commutes with view



# Limitations

- Views are injective
  - generalization might make propagators non contracting
  - studied in [1,2]
- Views map values for single variable
  - generalization might make propagators non contracting
  - studied in [1]
- Propagator invariants might be violated (rare)
  - propagators typically rely on variable domain invariants
  - example
    - adjusting lower bound of set variable does not change upper bound
    - might be violated by view

[1] Correia, Barahona. View-based propagation of decomposable constraints, Constraints, 2013.

[2] Van Hentenryck, Michel. Domain views for constraint programming, CP 2014.

# Not a Limitation

- Approach works **for any propagator**
- No restriction to bounds consistency

Techniques: transformation, generalization,  
specialization, type conversion, enforcing invariants

## USING VIEWS

# Transformation: Boolean

- Use **negation views** defined as

$$\varphi_x(v) = 1 - v$$

to derive

- $\neg x = y$  from  $x = y$  (on  $x$ )
- $x \wedge y = z$  from  $x \vee y = z$  (on  $x, y, z$ )
- $x \rightarrow y = z$  from  $x \vee y = z$  (on  $x$ )
- $x \oplus y = z$  from  $x \leftrightarrow y = z$  (on  $z$ )
  
- $x_1 \wedge \dots \wedge x_n \wedge \neg y_1 \wedge \dots \wedge \neg y_n = z$   
from  $x_1 \vee \dots \vee x_n \vee \neg y_1 \vee \dots \vee \neg y_n = z$  (on all)
  
- $x_1 \wedge \dots \wedge x_n \wedge \neg y_1 \wedge \dots \wedge \neg y_n = 0$   
from  $x_1 \vee \dots \vee x_n \vee \neg y_1 \vee \dots \vee \neg y_n = 1$  (on all)
  - optimized implementation with watched literals re-used!

# Transformation: Boolean

- Use negation views to derive
  - $x_1 + \dots + x_n \leq c$  from  $x_1 + \dots + x_n \geq c$  (c integer)  
as  $x_1 + \dots + x_n \leq c \Leftrightarrow \neg x_1 + \dots + \neg x_n \geq n - c$
  - $(x_1 + \dots + x_n \neq c) \Leftrightarrow y$  (c integer)  
from  $(x_1 + \dots + x_n = c) \Leftrightarrow y$ 
    - same idea for many reified constraints

# Transformation: Set

- **Complement view**: analogous to negation view
- Intersection from union, set difference from union, ...

# Transformation: Integer

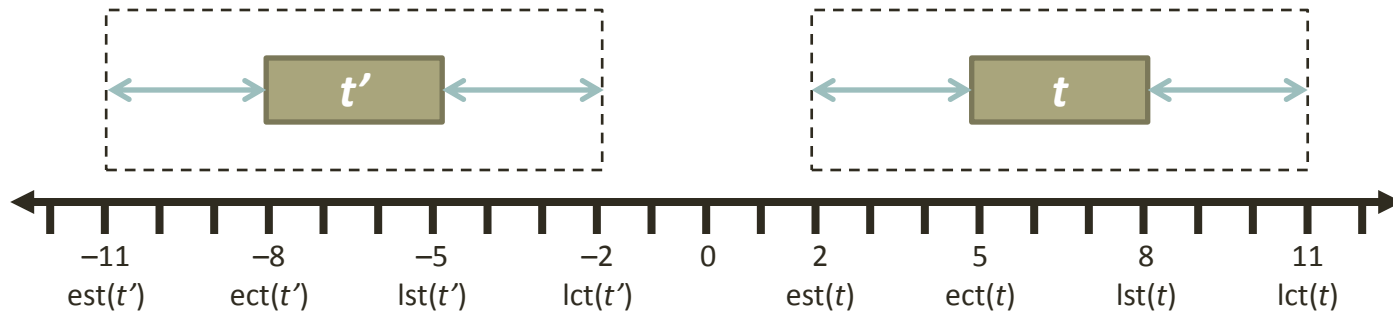
- Use **minus views** defined as

$$\varphi_x(v) = -v$$

to derive

- $\min(x, y) = z$  from  $\max(x, y) = z$  (on  $x, y, z$ )
  - bounds-consistent propagator (bounds(**Z**))
  - domain-consistent propagator
- $\min(x_1, \dots, x_n) = y$  from  $\max(x_1, \dots, x_n) = y$  (on  $x_1, \dots, x_n, y$ )
  - bounds-consistent propagator (bounds(**Z**))
  - domain-consistent propagator

# Transformation: Scheduling



- Scheduling propagators implemented in terms of
 

$est(t) \equiv$ earliest start time	$ect(t) \equiv$ earliest completion time
$lst(t) \equiv$ latest start time	$lct(t) \equiv$ latest completion time
  - Two variants needed
    - primary:  $t$  is not first  $\rightarrow$  adjust  $est(t)$
    - dual:  $t$  is not last  $\rightarrow$  adjust  $lct(t)$
  - Dual can be derived with minus views (mirror at 0-origin)
 
$$est(t') = -lct(t), \quad ect(t') = -lst(t), \quad lst(t') = -ect(t), \quad lct(t') = -est(t)$$
  - Can reuse complex data structures, for example  $\Omega$ -trees
- [Vilím.  $O(n \log n)$  filtering algorithms for unary resource constraints, CP AI OR 2004]



# Generalization

- Use **scale view** for integer  $a$  defined as

$$\varphi_x(v) = a \times v$$

to derive

$$a_1 \times x_1 + \dots + a_n \times x_n = c$$

from

$$x_1 + \dots + x_n = c$$

- Use **offset view** for integer  $o$  defined as

$$\varphi_x(v) = v + o$$

to derive

$$\text{alldifferent}(x_1 + c_1, \dots, x_n + c_n)$$

from

$$\text{alldifferent}(x_1, \dots, x_n)$$

# Specialization

- **Constant view** behaves like an assigned variable
  - less memory
  - more efficient code if constant known at compile time
- Derive
  - $x + y \leq c$  from  $x + y + z \leq c$  (use 0 for  $z$ )
  - $(x = c) \leftrightarrow b$  from  $(x = y) \leftrightarrow b$  (use  $c$  for  $y$ )
  - $|\{i \mid x_i = c\}| = z$  and  $|\{i \mid x_i = y\}| = c$   
from  $|\{i \mid x_i = y\}| = z$  (use  $c$  for  $y$  or  $z$ )
  - $\text{disjoint}(x,y)$  from  $x \cap y = z$  (use  $\emptyset$  for  $z$ )

# Type Conversion

- **Integer view** wraps Boolean 0/1 variable as an integer variable
  - 0/1 variables might have a more efficient implementation
  - all integer propagators can now be on 0/1 variables
  - some propagators should be still specific to 0/1 variables (linear inequalities due to watched literals, ...)
- **Singleton view** wraps integer variable as a set variable
  - derive  $x \in y$  from  $x \subseteq y$

# Enforcing Invariants

- Assume bounds(**Z**)-consistent propagator for  $x \times y = z$ 
  - propagation depends on whether 0 in  $x$ , 0 in  $y$ , or 0 in  $z$
- Direct implementation: convoluted and inefficient
- Rewriting: replace propagator if 0 excluded
  - $x > 0 \wedge y > 0 \wedge z > 0$ , or
  - $x > 0 \vee y > 0$ , or
  - $z > 0$

requires three different propagators

- Derivation: derive all from single propagator with minus views

# Enforcing Invariants

- Implementation of

binpacking( $l_1, \dots, l_m, b_1, \dots, b_n, s_1, \dots, s_n$ )

with

- load variables:  $l_j$  is the load of bin  $j$
- bin variables: item  $i$  with size  $s_i$  is packed into bin  $b_i$   
[Shaw. A constraint for bin packing, CP 2004]
- Enforce that all items are not yet packed
  - use offset views  $l_j + c_j$  for load variables
  - when item  $i$  is packed into bin  $j$  (bin variable  $b_i$  assigned to  $j$ ):
    - subtract size  $s_i$  from load offset  $c_j$
    - eliminate item  $i$  from  $b$  and  $s$
  - simplifies implementation and saves memory

# IMPLEMENTATION IDEA

# Integer Variable

```
class IntVar {  
    private: int _min, _max;  
    public:  int min(void) { return _min; }  
           int max(void) { return _max; }  
           void adjmin(int n) {  
               if (n > _min) _min = n;  
           }  
           void adjmax(int n) { ... }  
};
```

- Object-oriented model (ILOG Solver, Choco, Gecode, ...)
    - variables are objects
    - propagators are objects
- [Puget. A C++ Implementation of CLP, SPICIS 1994]

# Minus View

```
class MinusView {  
protected: IntVar* x;  
public:    MinusView(IntVar* x0)  
          : x(x0) {}  
int min(void) { return -x->max(); }  
int max(void) { return -x->min(); }  
void adjmin(int n) {  
    x->adjmax(-n);  
}  
void adjmax(int n) { ... }  
};
```

- Implements exactly same interface



# Propagator

```
template<class VX, class VY>
class LessThan : public Propagator {
protected: VX* x; VY* y;
public:     LessThan(VX* x0, VY* y0) : x(x0), y(y0) { ... }
          virtual void propagate(void) {
              x->adjmax(y->max()-1);
              y->adjmin(x->min()+1);
          }
};
```

- Propagators are parametric with respect to their views
- Creation of  $x < y$ :

```
new LessThan<IntVar,IntVar>(x,y);
```

- Creation of  $x > y$ :

```
new LessThan<MinusView,MinusView>(new MinusView(x),
                                   new MinusView(y));
```

# Choice of Parametricity

- Two variants available
  - parametric polymorphism (templates in C++, higher-order functions in Haskell, ...) **more efficient**
  - dynamic binding (virtual functions in C++, methods in Java) **more expressive**
- Gecode uses templates in C++
  - polymorphism resolved at compile time
  - some views optimized away entirely

# Domain Operations

- Operations that adjust the whole domain
- Efficient architecture based on range iterators
  - each range (interval) can be obtained in sequential order, one at a time
  - no data structures required
  - operations for views easily defined per range
- Details and evaluation in paper

# COST AND BENEFITS

# Return on Investment

variable type	implemented	derived	ratio
integer	93	377	4.05
Boolean 0/1	30	93	3.10
integer set	31	146	4.71
<b>overall</b>	<b>154</b>	<b>616</b>	<b>4.00</b>

- Propagator implementations:  $\approx$  40 000 lines of code  
 $\approx$  21 000 lines of documentation
- Views save :  $\approx$  120 000 lines of code  
 $\approx$  60 000 lines of documentation
- View implementations:  $\approx$  8 000 lines of code and doc
- Return on investment:  $\approx$  1 500 %

[Gecode 3.7.2]

# Evaluation Summary

- Decomposition always worse than views
  - integer benchmarks            126% more time            (14% ... 485%)  
   101% more memory        (2% ... 267%)
  - set benchmarks                 46% more time             (12% ... 131%)  
   31% more memory         (2% ... 144%)
- Minus and negation views for free
  - often optimized away by compiler
  - benchmarks using minus views on alldifferent confirm
- Complement view for sets not for free
  - 32% overhead compared to handwritten propagators

# Evaluation Summary

- Virtual methods worse than templates
  - integer benchmarks            34% more time        (5% ... 118%)
  - set benchmarks                18% more time        (9% ... 126%)
- template                        = compile-time polymorphism
- virtual method                = run-time polymorphism

# SUMMARY



# Related Approaches

- Indexicals and ILOG expressions
  - indexicals: uni-directional, more expressive
  - expressions: bi-directional, more expressive, no guarantees on update
- SAT literals use negation views (for example MiniSat)
- Views in other systems
  - Minion, CaSPER, Objective CP
  - useful for lazy clause generation

[References and extensive discussion in paper]

# Take Home

- Views = useful compromise  
efficiency  $\Leftrightarrow$  expressiveness
- Systematic derivation techniques
- Can be build on top of any system
  - needs some form of parametricity
- Gecode without views would have been...  
**slow** or **impossible**

# Integer Variable

```
class IntVar {  
    private: int _min, _max;  
    public:  int min(void) { return _min; }  
           int max(void) { return _max; }  
           void adjmin(int n) {  
               if (n > _min) _min = n;  
           }  
           void adjmax(int n) { ... }  
           void subscribe(EventSet e) { ... }  
};
```

- Object-oriented model (ILOG Solver, Choco, Gecode, ...)
    - variables are objects
    - propagators are objects
- [Puget. A C++ Implementation of CLP, SPICIS 1994]

# Offset View

```
class OffsetView {  
protected: IntVar* x; int c;  
public:    OffsetView(IntVar* x0, int c0)  
           : x(x0), c(c0) {}  
int min(void) { return x->min()+c; }  
int max(void) { return x->max()+c; }  
void adjmin(int n) {  
    x->adjmin(n-c);  
}  
void adjmax(int n) { ... }  
void subscribe(EventSet e) {  
    x->subscribe(e);  
}  
};
```

- Implements same interface as variable

# Minus View

```
class MinusView {  
protected: IntVar* x;  
public:    MinusView(IntVar* x0)  
          : x(x0) {}  
int min(void) { return -x->max(); }  
int max(void) { return -x->min(); }  
void adjmin(int n) {  
    x->adjmax(-n);  
}  
void adjmax(int n) { ... }  
void subscribe(EventSet e) {  
    x->subscribe(negate(e));  
}  
};
```

# Constant View

```
class ConstView {  
protected: int c;  
public:    ConstView(int c0)  
           : c(c0) {}  
int min(void) { return c; }  
int max(void) { return c; }  
void adjmin(int n) {  
    if (n > c) fail();  
}  
void adjmax(int n) { ... }  
void subscribe(EventSet e) {  
    schedule();  
}  
};
```

# Propagator

```
template<class VX, class VY>
class LessThan : public Propagator {
protected: VX* x; VY* y;
public:    LessThan(VX* x0, VY* y0) : x(x0), y(y0) {
          x->subscribe(LOWER_BOUND); y->subscribe(UPPER_BOUND);
          }
          virtual void propagate(void) {
          x->adjmax(y->max()-1); y->adjmin(x->min()+1);
          }
};
```

- Propagators are parametric with respect to their views
- Creation of  $x < y$ :

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- Creation of  $x > y$ :

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